

# NAG Library Function Document

## nag\_stable\_sort (m01ctc)

### 1 Purpose

nag\_stable\_sort (m01ctc) rearranges a vector of arbitrary type objects into ascending or descending order.

### 2 Specification

```
#include <nag.h>
#include <nagm01.h>

void nag_stable_sort (Pointer vec, size_t n, size_t size, ptrdiff_t stride,
                    Integer (*compare)(const Nag_Pointer a, const Nag_Pointer b),
                    Nag_SortOrder order, NagError *fail)
```

### 3 Description

nag\_stable\_sort (m01ctc) sorts a set of  $n$  data objects of arbitrary type, which are stored in the elements of an array at intervals of length **stride**. The function may be used to sort a column of a two-dimensional array. Either ascending or descending sort order may be specified.

A stable sort is one which preserves the order of distinct data items that compare equal. This function uses nag\_rank\_sort (m01dsc), nag\_make\_indices (m01zac) and nag\_reorder\_vector (m01esc) in order to carry out a stable sort with the same specification as nag\_quicksort (m01csc). nag\_stable\_sort (m01ctc) will be faster than nag\_quicksort (m01csc) if the comparison function **compare** is slow or the data items are large. Internally a large amount of workspace may be required compared with nag\_quicksort (m01csc).

### 4 References

Knuth D E (1973) *The Art of Computer Programming (Volume 3)* (2nd Edition) Addison–Wesley

### 5 Arguments

- 1: **vec[n]** – Pointer *Input/Output*  
*On entry:* the array of objects to be sorted.  
*On exit:* the objects rearranged into sorted order.
- 2: **n** – size\_t *Input*  
*On entry:* the number  $n$  of objects to be sorted.  
*Constraint:*  $0 \leq \mathbf{n} \leq \text{MAX\_LENGTH}$ , where MAX\_LENGTH is an implementation-dependent value for the maximum size of an array.
- 3: **size** – size\_t *Input*  
*On entry:* the size of each object to be sorted.  
*Constraint:*  $1 \leq \mathbf{size} \leq p$ , where  $p$  is an implementation-dependent value for the maximum size\_t size on the system, divided by **n** if **n** is positive.

4: **stride** – ptrdiff\_t *Input*

*On entry:* the increment between data items in **vec** to be sorted.

**Note:** if **stride** is positive, **vec** should point at the first data object; otherwise **vec** should point at the last data object.

*Constraint:*  $\mathbf{size} \leq |\mathbf{stride}| \leq p$ , where  $p$  is an implementation-dependent value for the maximum size\_t size on the system, divided by  $\mathbf{n}$  if  $\mathbf{n}$  is positive.

5: **compare** – function, supplied by the user *External Function*

nag\_stable\_sort (m01ctc) compares two data objects. If its arguments are pointers to a structure, this function must allow for the offset of the data field in the structure (if it is not the first).

The function must return:

- 1 if the first data field is less than the second,
- 0 if the first data field is equal to the second,
- 1 if the first data field is greater than the second.

The specification of **compare** is:

```
Integer compare (const Nag_Pointer a, const Nag_Pointer b)
```

1: **a** – const Nag\_Pointer *Input*

*On entry:* the first data field.

2: **b** – const Nag\_Pointer *Input*

*On entry:* the second data field.

6: **order** – Nag\_SortOrder *Input*

*On entry:* specifies whether the array is to be sorted into ascending or descending order.

*Constraint:* **order** = Nag\_Ascending or Nag\_Descending.

7: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_2\_INT\_ARG\_LT

*On entry,*  $|\mathbf{stride}| = \langle \mathit{value} \rangle$  while  $\mathbf{size} = \langle \mathit{value} \rangle$ . These arguments must satisfy  $|\mathbf{stride}| \geq \mathbf{size}$ .

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

### NE\_BAD\_PARAM

*On entry,* argument **order** had an illegal value.

### NE\_INT\_ARG\_GT

*On entry,*  $\mathbf{n} = \langle \mathit{value} \rangle$ .

*Constraint:*  $\mathbf{n} \leq \langle \mathit{value} \rangle$ , an implementation-dependent size that is printed in the error message.

*On entry,*  $\mathbf{size} = \langle \mathit{value} \rangle$ .

*Constraint:*  $\mathbf{size} \leq \langle \mathit{value} \rangle$ , an implementation-dependent size that is printed in the error message.

On entry, **stride** =  $\langle value \rangle$ .

Constraint:  $|\mathbf{stride}| \leq \langle value \rangle$ , an implementation-dependent size that is printed in the error message.

### NE\_INT\_ARG\_LT

On entry, **n** =  $\langle value \rangle$ .

Constraint:  $\mathbf{n} \geq 0$ .

On entry, **size** =  $\langle value \rangle$ .

Constraint:  $\mathbf{size} \geq 1$ .

## 7 Accuracy

Not applicable.

## 8 Parallelism and Performance

nag\_stable\_sort (m01ctc) is not threaded in any implementation.

## 9 Further Comments

The time taken by nag\_stable\_sort (m01ctc) is approximately proportional to  $n \log(n)$ .

## 10 Example

The example program reads a three column matrix of real numbers and sorts the first column into ascending order.

### 10.1 Program Text

```

/* nag_stable_sort (m01ctc) Example Program.
 *
 * NAGPRODCODE Version.
 *
 * Copyright 2016 Numerical Algorithms Group.
 *
 * Mark 26, 2016.
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nag_stddef.h>
#include <nagm01.h>

#ifdef __cplusplus
extern "C"
{
#endif
    static Integer NAG_CALL compare(const Nag_Pointer a, const Nag_Pointer b);
#ifdef __cplusplus
}
#endif

#define VEC(I, J) vec[(I) *tdvec + J]
int main(void)
{
    Integer exit_status = 0, i, j, k, m, n, tdvec;
    NagError fail;
    double *vec = 0;

    INIT_FAIL(fail);

```

```

/* Skip heading in data file */
#ifdef _WIN32
    scanf_s("%*[\n]");
#else
    scanf("%*[\n]");
#endif
printf("nag_stable_sort (m01ctc) Example Program Results\n");
#ifdef _WIN32
    scanf_s("%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "", &m, &n, &k);
#else
    scanf("%" NAG_IFMT "%" NAG_IFMT "%" NAG_IFMT "", &m, &n, &k);
#endif
if (m >= 0 && n >= 0 && k >= 0 && k <= n) {
    if (!(vec = NAG_ALLOC(m * n, double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    tdvec = n;
}
else {
    printf("Invalid m or n or k.\n");
    exit_status = 1;
    return exit_status;
}
for (i = 0; i < m; ++i)
    for (j = 0; j < n; ++j)
#ifdef _WIN32
    scanf_s("%lf", &VEC(i, j));
#else
    scanf("%lf", &VEC(i, j));
#endif
/* nag_stable_sort (m01ctc).
 * Stable sort of set of values of arbitrary data type
 */
nag_stable_sort((Pointer) &VEC(0, k - 1), (size_t) m, sizeof(double),
                (ptrdiff_t) (n * sizeof(double)), compare, Nag_Ascending,
                &fail);
if (fail.code != NE_NOERROR) {
    printf("Error from nag_stable_sort (m01ctc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

printf("\nMatrix with column %" NAG_IFMT " sorted\n", k);
for (i = 0; i < m; ++i) {
    for (j = 0; j < n; ++j)
        printf(" %7.1f ", VEC(i, j));
    printf("\n");
}
END:
NAG_FREE(vec);
return exit_status;
}

static Integer NAG_CALL compare(const Nag_Pointer a, const Nag_Pointer b)
{
    double x = *((const double *) a);
    double y = *((const double *) b);
    return (x < y ? -1 : (x == y ? 0 : 1));
}

```

## 10.2 Program Data

```
nag_stable_sort (m01ctc) Example Program Data
12 3 1
6.0 5.0 4.0
5.0 2.0 1.0
2.0 4.0 9.0
4.0 9.0 6.0
4.0 9.0 5.0
4.0 1.0 2.0
3.0 4.0 1.0
2.0 4.0 6.0
1.0 6.0 4.0
9.0 3.0 2.0
6.0 2.0 5.0
4.0 9.0 6.0
```

## 10.3 Program Results

```
nag_stable_sort (m01ctc) Example Program Results

Matrix with column 1 sorted
  1.0    5.0    4.0
  2.0    2.0    1.0
  2.0    4.0    9.0
  3.0    9.0    6.0
  4.0    9.0    5.0
  4.0    1.0    2.0
  4.0    4.0    1.0
  4.0    4.0    6.0
  5.0    6.0    4.0
  6.0    3.0    2.0
  6.0    2.0    5.0
  9.0    9.0    6.0
```

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