

## NAG Library Function Document

### **nag\_3d\_shep\_eval (e01thc)**

## 1 Purpose

nag\_3d\_shep\_eval (e01thc) evaluates the three-dimensional interpolating function generated by nag\_3d\_shep\_interp (e01tgc) and its first partial derivatives.

## 2 Specification

```
#include <nag.h>
#include <nage01.h>
void nag_3d_shep_eval (Integer m, const double x[], const double y[],
    const double z[], const double f[], const Integer iq[],
    const double rq[], Integer n, const double u[], const double v[],
    const double w[], double qx[], double qy[], double qz[],
    NagError *fail)
```

## 3 Description

nag\_3d\_shep\_eval (e01thc) takes as input the interpolant  $Q(x, y, z)$  of a set of scattered data points  $(x_r, y_r, z_r, f_r)$ , for  $r = 1, 2, \dots, m$ , as computed by nag\_3d\_shep\_interp (e01tgc), and evaluates the interpolant and its first partial derivatives at the set of points  $(u_i, v_i, w_i)$ , for  $i = 1, 2, \dots, n$ .

nag\_3d\_shep\_eval (e01thc) must only be called after a call to nag\_3d\_shep\_interp (e01tgc).

This function is derived from the function QS3GRD described by Renka (1988).

## 4 References

Renka R J (1988) Algorithm 661: QSHEP3D: Quadratic Shepard method for trivariate interpolation of scattered data *ACM Trans. Math. Software* **14** 151–152

## 5 Arguments

1:	<b>m</b> – Integer	<i>Input</i>
2:	<b>x[m]</b> – const double	<i>Input</i>
3:	<b>y[m]</b> – const double	<i>Input</i>
4:	<b>z[m]</b> – const double	<i>Input</i>
5:	<b>f[m]</b> – const double	<i>Input</i>

*On entry:* **m**, **x**, **y**, **z** and **f** must be the same values as were supplied in the preceding call to nag\_3d\_shep\_interp (e01tgc).

6:	<b>iq[(2 × m + 1)]</b> – const Integer	<i>Input</i>
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*On entry:* must be unchanged from the value returned from a previous call to nag\_3d\_shep\_interp (e01tgc).

7:	<b>rq[(10 × m + 7)]</b> – const double	<i>Input</i>
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*On entry:* must be unchanged from the value returned from a previous call to nag\_3d\_shep\_interp (e01tgc).

8:	<b>n</b> – Integer	<i>Input</i>
<i>On entry:</i> $n$ , the number of evaluation points.		
<i>Constraint:</i> $n \geq 1$ .		
9:	<b>u[n]</b> – const double	<i>Input</i>
10:	<b>v[n]</b> – const double	<i>Input</i>
11:	<b>w[n]</b> – const double	<i>Input</i>
<i>On entry:</i> $\mathbf{u}[i-1]$ , $\mathbf{v}[i-1]$ , $\mathbf{w}[i-1]$ must be set to the evaluation point $(u_i, v_i, w_i)$ , for $i = 1, 2, \dots, n$ .		
12:	<b>q[n]</b> – double	<i>Output</i>
<i>On exit:</i> $\mathbf{q}[i-1]$ contains the value of the interpolant at $(u_i, v_i, w_i)$ , for $i = 1, 2, \dots, n$ . If any of these evaluation points lie outside the region of definition of the interpolant the corresponding entries in <b>q</b> are set to the largest machine representable number (see <code>nag_real_largest_number</code> (X02ALC)), and <code>nag_3d_shep_eval</code> (e01thc) returns with <b>fail.code</b> = NE_BAD_POINT.		
13:	<b>qx[n]</b> – double	<i>Output</i>
14:	<b>qy[n]</b> – double	<i>Output</i>
15:	<b>qz[n]</b> – double	<i>Output</i>
<i>On exit:</i> $\mathbf{qx}[i-1]$ , $\mathbf{qy}[i-1]$ , $\mathbf{qz}[i-1]$ contains the value of the partial derivatives of the interpolant $Q(x, y, z)$ at $(u_i, v_i, w_i)$ , for $i = 1, 2, \dots, n$ . If any of these evaluation points lie outside the region of definition of the interpolant, the corresponding entries in <b>qx</b> , <b>qy</b> and <b>qz</b> are set to the largest machine representable number (see <code>nag_real_largest_number</code> (X02ALC)), and <code>nag_3d_shep_eval</code> (e01thc) returns with <b>fail.code</b> = NE_BAD_POINT.		
16:	<b>fail</b> – NagError *	<i>Input/Output</i>
The NAG error argument (see Section 3.6 in the Essential Introduction).		

## 6 Error Indicators and Warnings

### NE\_BAD\_PARAM

On entry, argument  $\langle\text{value}\rangle$  had an illegal value.

### NE\_BAD\_POINT

On entry, at least one evaluation point lies outside the region of definition of the interpolant. At all such points the corresponding values in **q**, **qx**, **qy** and **qz** have been set to `nag_real_largest_number`: `nag_real_largest_number` =  $\langle\text{value}\rangle$ .

### NE\_INT

On entry,  $\mathbf{m} = \langle\text{value}\rangle$ .  
Constraint:  $\mathbf{m} \geq 10$ .

On entry,  $\mathbf{n} = \langle\text{value}\rangle$ .  
Constraint:  $\mathbf{n} \geq 1$ .

### NE\_INT\_ARRAY

On entry, values in **iq** appear to be invalid. Check that **iq** has not been corrupted between calls to `nag_3d_shep_interp` (e01tgc) and `nag_3d_shep_eval` (e01thc).

### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

## NE\_REAL\_ARRAY

On entry, values in **rq** appear to be invalid. Check that **rq** has not been corrupted between calls to nag\_3d\_shep\_interp (e01tgc) and nag\_3d\_shep\_eval (e01thc).

## 7 Accuracy

Computational errors should be negligible in most practical situations.

## 8 Parallelism and Performance

nag\_3d\_shep\_eval (e01thc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

Please consult the Users' Note for your implementation for any additional implementation-specific information.

## 9 Further Comments

The time taken for a call to nag\_3d\_shep\_eval (e01thc) will depend in general on the distribution of the data points. If **x**, **y** and **z** are approximately uniformly distributed, then the time taken should be only  $O(n)$ . At worst  $O(mn)$  time will be required.

## 10 Example

See Section 10 in nag\_3d\_shep\_interp (e01tgc).

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