

NAG Library Function Document

nag_bessel_y1 (s17adc)

1 Purpose

nag_bessel_y1 (s17adc) returns the value of the Bessel function $Y_1(x)$.

2 Specification

```
#include <nag.h>
#include <nags.h>
double nag_bessel_y1 (double x, NagError *fail)
```

3 Description

nag_bessel_y1 (s17adc) evaluates an approximation to the Bessel function of the second kind $Y_1(x)$.

Note: $Y_1(x)$ is undefined for $x \leq 0$ and the function will fail for such arguments.

The function is based on four Chebyshev expansions:

For $0 < x \leq 8$,

$$Y_1(x) = \frac{2}{\pi} \ln x \frac{x}{8} \sum_{r=0} a_r T_r(t) - \frac{2}{\pi x} + \frac{x}{8} \sum_{r=0} b_r T_r(t), \quad \text{with } t = 2\left(\frac{x}{8}\right)^2 - 1.$$

For $x > 8$,

$$Y_1(x) = \sqrt{\frac{2}{\pi x}} \left\{ P_1(x) \sin\left(x - 3\frac{\pi}{4}\right) + Q_1(x) \cos\left(x - 3\frac{\pi}{4}\right) \right\}$$

where $P_1(x) = \sum_{r=0} c_r T_r(t)$,

and $Q_1(x) = \frac{8}{x} \sum_{r=0} d_r T_r(t)$, with $t = 2\left(\frac{8}{x}\right)^2 - 1$.

For x near zero, $Y_1(x) \simeq -\frac{2}{\pi x}$. This approximation is used when x is sufficiently small for the result to be correct to **machine precision**. For extremely small x , there is a danger of overflow in calculating $-\frac{2}{\pi x}$ and for such arguments the function will fail.

For very large x , it becomes impossible to provide results with any reasonable accuracy (see Section 7), hence the function fails. Such arguments contain insufficient information to determine the phase of oscillation of $Y_1(x)$; only the amplitude, $\sqrt{\frac{2}{\pi x}}$, can be determined and this is returned on failure. The range for which this occurs is roughly related to **machine precision**; the function will fail if $x \gtrsim 1/\text{machine precision}$ (see the Users' Note for your implementation for details).

4 References

Abramowitz M and Stegun I A (1972) *Handbook of Mathematical Functions* (3rd Edition) Dover Publications

Clenshaw C W (1962) Chebyshev Series for Mathematical Functions *Mathematical tables* HMSO

5 Arguments

- 1: **x** – double *Input*
On entry: the argument x of the function.
Constraint: $x > 0.0$.
- 2: **fail** – NagError * *Input/Output*
 The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

NE_REAL_ARG_GT

On entry, $x = \langle value \rangle$.
 Constraint: $x \leq \langle value \rangle$.
 x is too large, the function returns the amplitude of the Y_1 oscillation, $\sqrt{2/(\pi x)}$.

NE_REAL_ARG_LE

On entry, $x = \langle value \rangle$.
 Constraint: $x > 0.0$.
 Y_1 is undefined, the function returns zero.

NE_REAL_ARG_TOO_SMALL

x is too close to zero and there is danger of overflow, $x = \langle value \rangle$.
 Constraint: $x > \langle value \rangle$.
 The function returns the value of $Y_1(x)$ at the smallest valid argument.

7 Accuracy

Let δ be the relative error in the argument and E be the absolute error in the result. (Since $Y_1(x)$ oscillates about zero, absolute error and not relative error is significant, except for very small x .)

If δ is somewhat larger than the *machine precision* (e.g., if δ is due to data errors etc.), then E and δ are approximately related by:

$$E \simeq |xY_0(x) - Y_1(x)|\delta$$

(provided E is also within machine bounds). Figure 1 displays the behaviour of the amplification factor $|xY_0(x) - Y_1(x)|$.

However, if δ is of the same order as *machine precision*, then rounding errors could make E slightly larger than the above relation predicts.

For very small x , absolute error becomes large, but the relative error in the result is of the same order as δ .

For very large x , the above relation ceases to apply. In this region, $Y_1(x) \simeq \sqrt{\frac{2}{\pi x}} \sin\left(x - \frac{3\pi}{4}\right)$. The amplitude $\sqrt{\frac{2}{\pi x}}$ can be calculated with reasonable accuracy for all x , but $\sin\left(x - \frac{3\pi}{4}\right)$ cannot. If $x - \frac{3\pi}{4}$ is written as $2N\pi + \theta$ where N is an integer and $0 \leq \theta < 2\pi$, then $\sin\left(x - \frac{3\pi}{4}\right)$ is determined by θ only. If $x > \delta^{-1}$, θ cannot be determined with any accuracy at all. Thus if x is greater than, or of the order of,

the inverse of the *machine precision*, it is impossible to calculate the phase of $Y_1(x)$ and the function must fail.

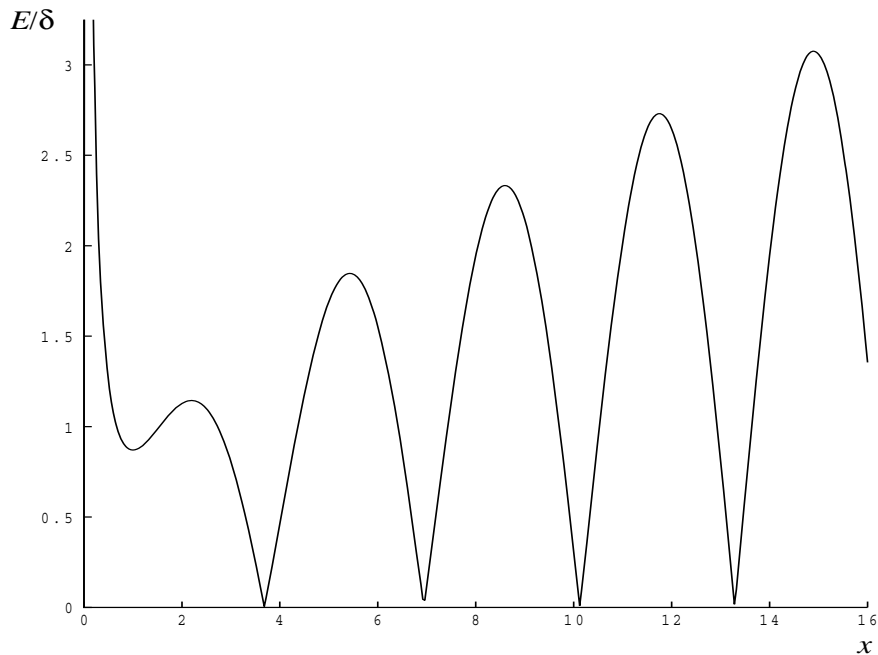


Figure 1

8 Parallelism and Performance

Not applicable.

9 Further Comments

None.

10 Example

This example reads values of the argument x from a file, evaluates the function at each value of x and prints the results.

10.1 Program Text

```
/* nag_bessel_y1 (s17adc) Example Program.
 *
 * Copyright 1990 Numerical Algorithms Group.
 *
 * Mark 2 revised, 1992.
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nags.h>

int main(void)
{
    Integer    exit_status = 0;
    double     x, y;
    NagError   fail;

    INIT_FAIL(fail);
```

```

/* Skip heading in data file */
scanf("%*[\n]");
printf("nag_bessel_y1 (s17adc) Example Program Results\n");
printf("      x          y\n");
while (scanf("%lf", &x) != EOF)
{
  /* nag_bessel_y1 (s17adc).
   * Bessel function Y_1(x)
   */
  y = nag_bessel_y1(x, &fail);
  if (fail.code != NE_NOERROR)
  {
    printf("Error from nag_bessel_y1 (s17adc).\n%s\n",
           fail.message);
    exit_status = 1;
    goto END;
  }
  printf("%12.3e%12.3e\n", x, y);
}

END:
return exit_status;
}

```

10.2 Program Data

```

nag_bessel_y1 (s17adc) Example Program Data
      0.5
      1.0
      3.0
      6.0
      8.0
      10.0
      1000.0

```

10.3 Program Results

```

nag_bessel_y1 (s17adc) Example Program Results
      x          y
5.000e-01 -1.471e+00
1.000e+00 -7.812e-01
3.000e+00  3.247e-01
6.000e+00 -1.750e-01
8.000e+00 -1.581e-01
1.000e+01  2.490e-01
1.000e+03 -2.478e-02

```

