NAG Library Routine Document F08KCF (DGELSD)

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of **bold italicised** terms and other implementation-dependent details.

1 Purpose

F08KCF (DGELSD) computes the minimum norm solution to a real linear least squares problem

$$\min \|b - Ax\|_2.$$

2 Specification

```
SUBROUTINE F08KCF (M, N, NRHS, A, LDA, B, LDB, S, RCOND, RANK, WORK, LWORK, IWORK, INFO)

INTEGER M, N, NRHS, LDA, LDB, RANK, LWORK, IWORK(*), INFO

REAL (KIND=nag_wp) A(LDA,*), B(LDB,*), S(*), RCOND, WORK(max(1,LWORK))
```

The routine may be called by its LAPACK name dgelsd.

3 Description

F08KCF (DGELSD) uses the singular value decomposition (SVD) of A, where A is a real m by n matrix which may be rank-deficient.

Several right-hand side vectors b and solution vectors x can be handled in a single call; they are stored as the columns of the m by r right-hand side matrix B and the n by r solution matrix X.

The problem is solved in three steps:

- 1. reduce the coefficient matrix A to bidiagonal form with Householder transformations, reducing the original problem into a 'bidiagonal least squares problem' (BLS);
- 2. solve the BLS using a divide-and-conquer approach;
- 3. apply back all the Householder transformations to solve the original least squares problem.

The effective rank of A is determined by treating as zero those singular values which are less than RCOND times the largest singular value.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia http://www.netlib.org/lapack/lug

Golub G H and Van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

1: M – INTEGER Input

On entry: m, the number of rows of the matrix A.

Constraint: $M \ge 0$.

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2: N – INTEGER Input

On entry: n, the number of columns of the matrix A.

Constraint: $N \ge 0$.

3: NRHS – INTEGER Input

On entry: r, the number of right-hand sides, i.e., the number of columns of the matrices B and X. Constraint: NRHS ≥ 0 .

4: A(LDA,*) – REAL (KIND=nag wp) array

Input/Output

Note: the second dimension of the array A must be at least max(1, N).

On entry: the m by n coefficient matrix A.

On exit: the contents of A are destroyed.

5: LDA – INTEGER Input

On entry: the first dimension of the array A as declared in the (sub)program from which F08KCF (DGELSD) is called.

Constraint: LDA $\geq \max(1, M)$.

6: $B(LDB,*) - REAL (KIND=nag_wp)$ array

Input/Output

Note: the second dimension of the array B must be at least max(1, NRHS).

On entry: the m by r right-hand side matrix B.

On exit: B is overwritten by the n by r solution matrix X. If $m \ge n$ and RANK = n, the residual sum of squares for the solution in the ith column is given by the sum of squares of elements $n+1,\ldots,m$ in that column.

7: LDB – INTEGER Input

On entry: the first dimension of the array B as declared in the (sub)program from which F08KCF (DGELSD) is called.

Constraint: LDB $\geq \max(1, M, N)$.

8: $S(*) - REAL (KIND=nag_wp) array$

Output

Note: the dimension of the array S must be at least max(1, min(M, N)).

On exit: the singular values of A in decreasing order.

9: RCOND - REAL (KIND=nag_wp)

Input

On entry: used to determine the effective rank of A. Singular values $S(i) \leq RCOND \times S(1)$ are treated as zero. If RCOND < 0, **machine precision** is used instead.

10: RANK – INTEGER

Output

On exit: the effective rank of A, i.e., the number of singular values which are greater than RCOND \times S(1).

11: WORK(max(1,LWORK)) – REAL (KIND=nag wp) array

Workspace

On exit: if INFO = 0, WORK(1) contains the minimum value of LWORK required for optimal performance.

12: LWORK – INTEGER

Input

On entry: the dimension of the array WORK as declared in the (sub)program from which F08KCF (DGELSD) is called.

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The exact minimum amount of workspace needed depends on M, N and NRHS. As long as LWORK is at least

$$12r + 2r \times smlsiz + 8r \times nlvl + r \times NRHS + (smlsiz + 1)^2$$
,

where smlsiz is equal to the maximum size of the subproblems at the bottom of the computation tree (usually about 25), $nlvl = \max(0, \inf(\log_2(\min(M, N)/(smlsiz + 1))) + 1)$ and $r = \min(M, N)$, the code will execute correctly.

If LWORK = -1, a workspace query is assumed; the routine only calculates the optimal size of the WORK array and the minimum size of the IWORK array, and returns these values as the first entries of the WORK and IWORK arrays, and no error message related to LWORK is issued.

Suggested value: for optimal performance, LWORK should generally be larger than the minimum required as set out above. Consider increasing LWORK by at least $nb \times \min(M, N)$, where nb is the optimal **block size**.

Constraint:

LWORK
$$\geq 12r + 2r \times smlsiz + 8r \times nlvl + r \times NRHS + (smlsiz + 1)^2$$
 or LWORK $= -1$.

13: IWORK(*) - INTEGER array

Workspace

Note: the dimension of the array IWORK must be at least $\max(1, liwork)$, where liwork is at least $\max(1, 3 \times \min(M, N) \times nlvl + 11 \times \min(M, N))$.

On exit: if INFO = 0, IWORK(1) returns the minimum liwork.

14: INFO – INTEGER Output

On exit: INFO = 0 unless the routine detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the routine:

INFO < 0

If INFO = -i, argument i had an illegal value. An explanatory message is output, and execution of the program is terminated.

INFO > 0

The algorithm for computing the SVD failed to converge; if INFO = i, i off-diagonal elements of an intermediate bidiagonal form did not converge to zero.

7 Accuracy

See Section 4.5 of Anderson et al. (1999) for details.

8 Further Comments

The complex analogue of this routine is F08KQF (ZGELSD).

9 Example

This example solves the linear least squares problem

$$\min_{x} \lVert b - Ax \rVert_2$$

for the solution, x, of minimum norm, where

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$$A = \begin{pmatrix} -0.09 & -1.56 & -1.48 & -1.09 & 0.08 & -1.59 \\ 0.14 & 0.20 & -0.43 & 0.84 & 0.55 & -0.72 \\ -0.46 & 0.29 & 0.89 & 0.77 & -1.13 & 1.06 \\ 0.68 & 1.09 & -0.71 & 2.11 & 0.14 & 1.24 \\ 1.29 & 0.51 & -0.96 & -1.27 & 1.74 & 0.34 \end{pmatrix} \quad \text{and} \quad b = \begin{pmatrix} 7.4 \\ 4.3 \\ -8.1 \\ 1.8 \\ 8.7 \end{pmatrix}$$

A tolerance of 0.01 is used to determine the effective rank of A.

Note that the block size (NB) of 64 assumed in this example is not realistic for such a small problem, but should be suitable for large problems.

9.1 Program Text

```
Program f08kcfe
!
      FO8KCF Example Program Text
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!
      .. Use Statements ..
     Use nag_library, Only: dgelsd, nag_wp
      .. Implicit None Statement ..
!
      Implicit None
      .. Parameters ..
      Integer, Parameter
.. Local Scalars ..
                                        :: nin = 5, nout = 6
      Real (Kind=nag_wp)
                                        :: rcond
      Integer
                                        :: i, info, lda, liwork, lwork, m, n,
                                           rank
      .. Local Arrays ..
!
      Real (Kind=nag_wp), Allocatable :: a(:,:), b(:), s(:), work(:)
     Real (Kind=nag_wp)
                                       :: lw(1)
                                        :: iwork(:)
      Integer, Allocatable
                                        :: liw(1)
      Integer
!
      .. Intrinsic Procedures ..
      Intrinsic
                                        :: nint
      .. Executable Statements ..
!
      Write (nout,*) 'FO8KCF Example Program Results'
      Write (nout,*)
      Skip heading in data file
      Read (nin,*)
      Read (nin,*) m, n
      lda = m
     Allocate (a(lda,n),b(n),s(m))
     Read A and B from data file
     Read (nin,*)(a(i,1:n),i=1,m)
      Read (nin,*) b(1:m)
      Choose RCOND to reflect the relative accuracy of the input
      data
      rcond = 0.01_nag_wp
!
      Call f08kcf/dgelsd in workspace query mode.
      lwork = -1
!
      The NAG name equivalent of dgelsd is f08kcf
      Call dgelsd(m,n,1,a,lda,b,n,s,rcond,rank,lw,lwork,liw,info)
      lwork = nint(lw(1))
      liwork = liw(1)
     Allocate (work(lwork),iwork(liwork))
     Now Solve the least squares problem min( norm2(b - Ax) ) for the
!
      x of minimum norm.
      Call dgelsd(m,n,1,a,lda,b,n,s,rcond,rank,work,lwork,iwork,info)
```

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```
If (info==0) Then
        Print solution
        Write (nout,*) 'Least squares solution'
        Write (nout, 99999) b(1:n)
        Print the effective rank of A
        Write (nout,*)
        Write (nout,*) 'Tolerance used to estimate the rank of A'
        Write (nout,99998) rcond
        Write (nout,*) 'Estimated rank of A'
        Write (nout,99997) rank
!
        Print singular values of A
        Write (nout,*)
        Write (nout,*) 'Singular values of A'
        Write (nout,99999) s(1:m)
      Else
        Write (nout,*) 'The SVD algorithm failed to converge'
      End If
99999 Format (1X,7F11.4)
99998 Format (3X,1P,E11.2)
99997 Format (1X,I6)
    End Program f08kcfe
9.2 Program Data
```

FO8KCF Example Program Data

```
5
                               :Values of M and N
      6
-0.09 -1.56 -1.48 -1.09 0.08 -1.59
-0.46
     1.09 -0.71 2.11
                    0.14
                          1.24
0.68
1.29 0.51 -0.96 -1.27 1.74 0.34 :End of matrix A
7.4
4.3
-8.1
1.8
8.7
                               :End of vector b
```

9.3 Program Results

```
FO8KCF Example Program Results
Least squares solution
                        -3.1501
                                  0.1554
                                             2.5529 -1.6730
    1.5938
             -0.1180
Tolerance used to estimate the rank of A
    1.00E-02
Estimated rank of A
    4
Singular values of A
    3.9997
             2.9962
                         2.0001
                                    0.9988
                                              0.0025
```

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